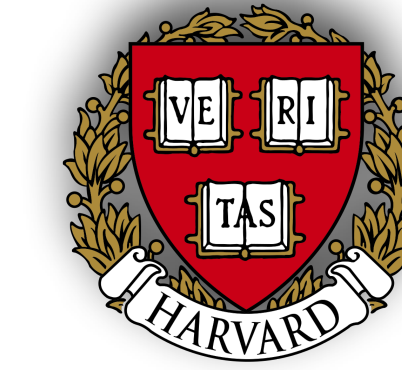
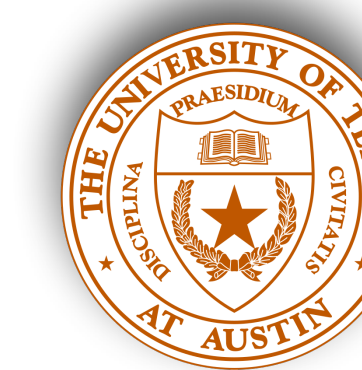




# Learning Mixtures of Gaussians Using the DDPM Objective

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Paper

## Diffusion Models: A Generative Modelling framework

- Backbone of the powerful models such as DALL-E 2, Imagen, Stable Diffusion and Dream-Fusion
- **Assuming the existence of an oracle for score estimation**, several work establishes convergence guarantees under mild assumptions on the data distribution [CCL+23, LLT23]

Are there any data distributions under which gradient descent provably achieves accurate score estimation?

## Forward and Backward Process

### Forward Corruption Process



$X_0 \sim q_0$  (Data distribution)  $X_t \sim q_t$  (Distribution at noise  $t$ )  $X_T \sim q_T$  ( $\approx$  Normal distribution)

Forward SDE:  $dX_t = -X_t dt + \sqrt{2}dW_t$  (Ornstein-Uhlenbeck process)

### Reverse Generative Process



Reverse SDE:  $dX_t^{\leftarrow} = (X_t^{\leftarrow} + 2 \nabla \ln q_{T-t}(X_t^{\leftarrow})) dt + \sqrt{2}dW_t$

Learning the score using score-matching at various noise scales:

$$s_{T-t} = \arg \min_s \mathbb{E}[\|s_{T-t}(X_t^{\leftarrow}) - \nabla \ln q_{T-t}(X_t^{\leftarrow})\|^2]$$

Denosing DDPM Objective [HJA20] and sliced score matching [SGSE19] are different ways to minimize the objective and equivalent to the score matching objective upto a data dependent constant.

## Takeaways

- Gradient Descent on the DDPM Objective learns parameters of
  - mixtures of two Gaussians from random initialization
  - mixtures of K Gaussians from warm initialization (First efficient learning results for diffusion models.)
- Our proofs use a new connection between score-based methods and two other approaches to distribution learning: the Expectation-Maximization (EM) algorithm and spectral methods.

## Mixtures of two Gaussians

Mixtures of two Gaussians:

$$q = 0.5\mathcal{N}(\mu^*, I) + 0.5\mathcal{N}(-\mu^*, I)$$

**Informal Result:** Gradient descent (GD) on the DDPM objective with random initialization efficiently learns the parameters of an unknown mixture of two spherical Gaussians with  $1/\text{poly}(\text{dimension})$ -separated centers.

## Proof Idea

$$\text{Population update} \approx \mathbb{E}[\underbrace{\tanh(\mu^{\top} x)x}_{\text{EM Update}} + \text{Other terms}]$$

### Large noise scale training:

- Population GD on DDPM objective  $\approx$  Power method on  $I + \mu^* \mu^{*\top}$  matrix (without normalization)
- Convergence of power method in angular distance  $\implies$  Warm start for the DDPM training

### Small noise scale training:

- Population GD on DDPM objective  $\approx$  Expectation-Maximization (EM) algorithm update
- Convergence of EM update  $\implies$  Convergence of DDPM training

## Mixtures of K Gaussians

Mixtures of K Gaussians with  $\Omega(\sqrt{\log(K)})$ -separated centers

$$q = \frac{1}{K} \sum_{i=1}^K \mathcal{N}(\mu_i^*, I) \quad \text{where } \mu_i^* = \text{mean of } i^{\text{th}} \text{ component}$$

**Informal Result:** When there is a warm start of the centers, gradient descent on the DDPM objective learns the parameters of the mixture of K Gaussians in polynomial time and sample complexity.

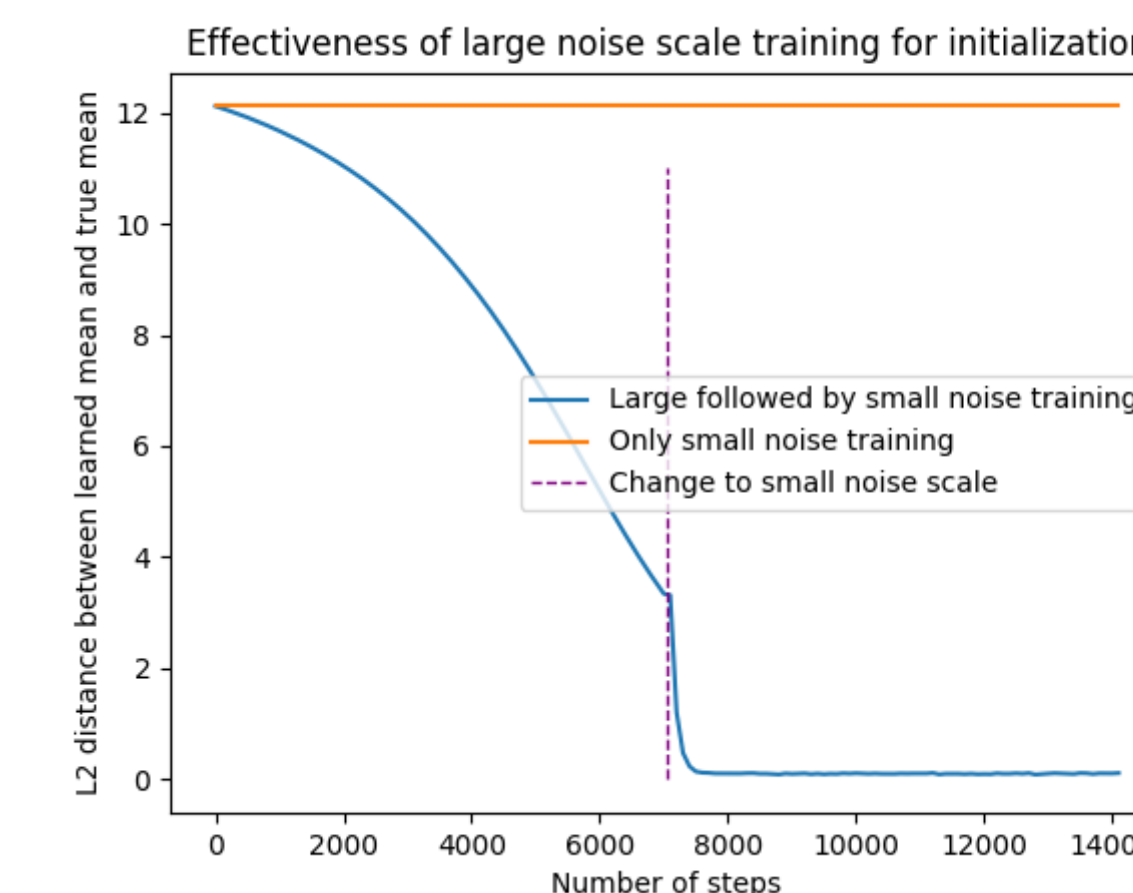
- Connection between Population GD on DDPM objective and EM algorithm extends to mixtures of K Gaussians.
- Known results on local convergence of EM [KC20, SN21] implies the learning.

## Experiments

**Task:** Learning mixtures of two Gaussians

### Observation:

- Large noise scale training provide warm start of the training
- Only small noise scale training does not converge to ground-truth parameters



## References

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